

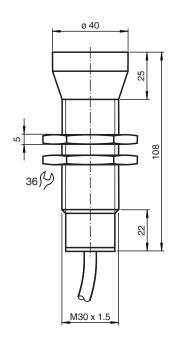
Ultrasonic sensor UB2000-30GM-H3-Y48481

- Separate evaluation
- Direct detection mode

Single head system



Dimensions



Technical Data

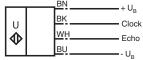
General specifications		
Sensing range		200 2000 mm
Dead band		0 200 mm
Standard target plate		100 mm x 100 mm
Transducer frequency		approx. 175 kHz
Electrical specifications		
Operating voltage	U _B	10 30 V DC , ripple 10 %ss
No-load supply current	I_0	≤ 30 mA
Input		

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Technical Data	
Input type	1 pulse input for transmitter pulse, activation through open collector npn < 1 V: emitter active, > 4 V: emitter inactive
Pulse length	20 200 μs
Pause length	≥ 50 x pulse length
Output	
Output type	1 pulse output for echo propagation time, high-active, short-circuit proof
Signal level	1-level: \geq U _B - 3 V; \leq 10 mA level 0: \leq 1 V; \leq 0,1 mA
Temperature influence	the echo propagation time: 0.17 % / K
Compliance with standards and directives	
Standard conformity	
Standards	EN IEC 60947-5-2:2020 IEC 60947-5-2:2019
Approvals and certificates	
UL approval	cULus Listed, General Purpose
CCC approval	CCC approval / marking not required for products rated ≤36 V
Ambient conditions	
Ambient temperature	-25 70 °C (-13 158 °F)
Storage temperature	-40 85 °C (-40 185 °F)
Mechanical specifications	
Housing diameter	30 mm
Degree of protection	IP65
Connection	2 m PVC cable 0.75 mm ²
Material	
Housing	nickel plated brass; plastic components: PBT
Transducer	epoxy resin/hollow glass sphere mixture; polyurethane foam
Mass	300 g

Connection

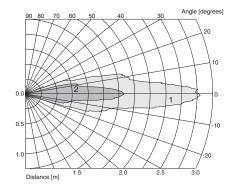
Standard symbol/Connection: (Transceiver)



BK = Emitter pulse input WH = Echo propagation time output

Characteristic Curve

Characteristic response curves



Curve 1: flat surface 100 mm x 100 mm

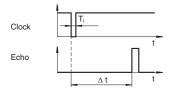
Curve 2: round bar, Ø 25 mm

Accessories BF 30 Mounting flange, 30 mm BF 30-F Plastic mounting adapter, 30 mm BF 5-30 Universal mounting bracket for cylindrical sensors with a diameter of 5 ... 30 mm UVW90-M30 Ultrasonic -deflector UVW90-K30 Ultrasonic -deflector M30K-VE Plastic nuts with centering ring for the vibration-free mounting of cylindrical sensors

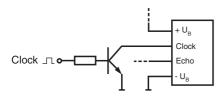
Commissioning

The sensing range is determined in the downstream evaluation electronics such as PLC modules or other existing evaluation units.

The object distance in pulse-echo mode is obtained from the echo time Δt . The emission of an ultrasonic pulse starts simultaneously with the falling slope of the clock input signal.



We recommend the usage of a npn-transistor to trigger the sensors clock input. The sensors clock input is connected to the +5 V potential internally by means of a pull up resistor.



 $^{^{1)}\,}$ The unusable area (blind range) BR depends on the pulse duration T $_{\rm I}$. The unusable area reaches a minimum with the shortest pulse duration 2

The sensors detection range depends on the pulse duration T_i. With a pulse shorter than the typical pulse duration, the sensors detection range may be reduced.