



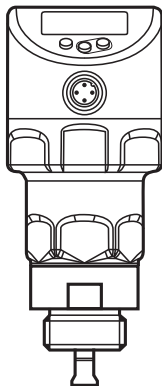
CE

Operating instructions
Electronic level sensor

LR2050

UK

80229610 / 02 01 / 2022



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1 Preliminary note

1.1 Symbols used

- ▶ Instructions
- > Reaction, result
- [...] Designation of keys, buttons or indications
- Cross-reference



Important note

Non-compliance may result in malfunction or interference.



Information

Supplementary note.

2 Safety instructions

- The device described is a subcomponent for integration into a system.
 - The manufacturer of the system is responsible for the safety of the system.
 - The system manufacturer undertakes to perform a risk assessment and to create a documentation in accordance with legal and normative requirements to be provided to the operator and user of the system. This documentation must contain all necessary information and safety instructions for the operator, the user and, if applicable, for any service personnel authorised by the manufacturer of the system.
- Read this document before setting up the product and keep it during the entire service life.
- The product must be suitable for the corresponding applications and environmental conditions without any restrictions.
- Only use the product for its intended purpose (→ Functions and features).
- Only use the product for permissible media (→ Technical data).
- If the operating instructions or the technical data are not adhered to, personal injury and/or damage to property may occur.
- The manufacturer assumes no liability or warranty for any consequences caused by tampering with the product or incorrect use by the operator.
- Installation, electrical connection, set-up, operation and maintenance of the unit must be carried out by qualified personnel authorised by the machine operator.
- Protect units and cables against damage.

3 Items supplied

- 1 LR2050 level sensor
- 1 operating instructions

In addition, the following is necessary for installation and operation (→ Accessories):

- 1 rod (→ 12.1)
 - as an option: 1 coaxial pipe (→ 12.2)
 - mounting material (if necessary, a launching plate) (→ 12.1)
- In the event of incomplete or damaged items supplied please contact ifm electronic.



- Only use accessories from ifm electronic.

Accessories: www.ifm.com

The optimum function is not ensured when using components from other manufacturers.

4 Getting started

For the most frequent applications the quick set-up described below is possible. The quick set-up does not replace observance of the other chapters.

- Install the unit correctly:
Installation distances (→ 7.1), Electrical connection (→ 8).
- Setting the type of probe, probe length and medium (→ 11.2).

> The unit is ready for operation.



Without changes = factory settings active (→ 15).

Change of the factory settings (→ 11).

- As an option, carry out a tank adjustment (→ 11.2.4).
- If necessary, make more settings for adaptation to the application (→ 11.3) and (→ 11.4).
- Check whether the unit operates correctly.

5 Functions and features

The unit continuously detects the level in tanks.

5.1 Application area

- Water, water-based media
- Oils, oil-based media (only for operation with coaxial probe)
- Compatible with G $\frac{3}{4}$ process connections

Application examples:

- Detection of cleaning liquid in a parts cleaning system
- Monitoring of hydraulic oil in a hydraulic power unit (only for operation with coaxial probe)
- Detection of cooling water in an industrial cooling system
- Detection of hot glue in corrugated cardboard manufacture

The unit complies with the standard EN 61000-6-4 and is a class A product.

The unit may cause radio interference in domestic areas. If interference occurs, the user must take appropriate actions.



The microwave energy radiated by the unit is much below that of mobile phones.

According to the current state of science the operation of the unit can be classified to be harmless to human health.

5.2 Restriction of the application area



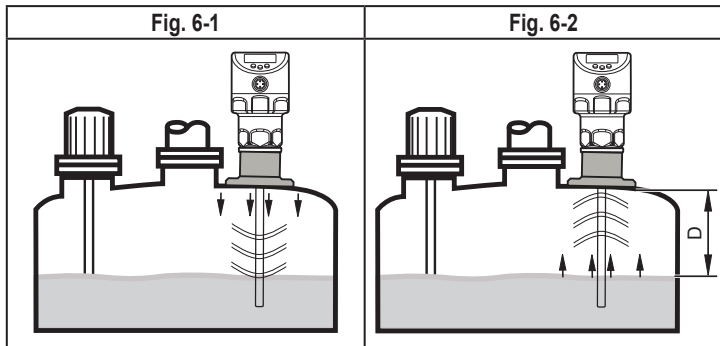
Incorrect measurements may be caused by the following media:

- Highly absorbing surfaces (e.g. foam).
 - Intensely bubbling surfaces.
 - Media which are very inhomogeneous, separate from each other thus forming separation layers (e.g. oil layer on water).
 - ▶ Check the function by performing an application test.
 - ▶ Installation in a steady area (→ 7.2.6).
 - > In case of signal loss, the unit displays [SEnS] and switches the outputs to a defined state (→ 12.8).
- The unit is not suitable for bulk materials (e.g. plastic granulates).

- The unit is not suitable for applications where the rod is subjected to permanent and high mechanical stress (e.g. fast moving viscous media or fast flowing media).
- In case of operation with single probe: use preferably in metal tanks. When used in plastic tanks, deterioration caused by electromagnetic interference may occur (noise immunity to EN61000-6-2). Corrective measures: (→ 7.6.4)
- When operating with a single probe and small tanks (probe lengths shorter than 200 mm and less than 300 mm distance to the tank wall), interference from the tank (resonances) may occur in rare cases. Corrective measures: (→ 7.1)
- In case of operation with coaxial probe: not suitable for soiled or viscous media, media containing solid particles and media prone to formation of deposit.
Maximum viscosity: 500 mPa · s

6 Function

6.1 Measuring principle



The unit operates on the principle of guided wave radar. It measures the level using electromagnetic pulses in the nanosecond range.

The pulses are transmitted by the sensor head and guided along the rod (fig. 6-1). When they hit the medium to be detected they are reflected and guided back to the sensor (fig. 6-2). The time between transmitting and receiving the pulse directly relates to the travelled distance (D) and the current level. The reference for distance measurement is the lower edge of the process connection.



The figures show the operation with single probe. In case of operation with a coaxial probe, the guided wave runs only along the inside of the coaxial pipe.

6.2 Outputs

The unit generates output signals according to the parameter setting. 2 outputs are available. They can be set separately.

OUT1	Switching signal for level limit value / IO-Link (→ 6.3.7)
OUT2	<ul style="list-style-type: none">• Analogue signal proportional to level 4...20 mA / 20...4 mA or• Switching signal for level limit value

6.3 Other features of the unit

- Increased temperature range, increased protection rating (→ Technical data sheet)
- Special operating mode for media with increased foam formation (→ 11.2.3)
- Tank adjustment enables suppression of undesired interference (e.g. caused by structures in the tank or when mounted in a connection piece (→ 11.2.4))
- Display of the level and the switching status via display / LEDs
- IO-Link function (→ 6.3.7)

6.3.1 Display functions

The unit displays the current level, either in mm, inch or in percent of the scaled measuring range. Factory setting: mm

The display unit is defined by programming (→ 11.3).

In the operating mode, the user can switch between the length display (mm / inch) and percentage (→ 12.6).

The set unit of measurement and the switching status of the outputs are indicated by LEDs (→ 9).

6.3.2 Analogue function

The unit provides an analogue signal proportional to the level. The analogue output (OUT2) can be set ((→ 11.4.6) and the following illustrations).

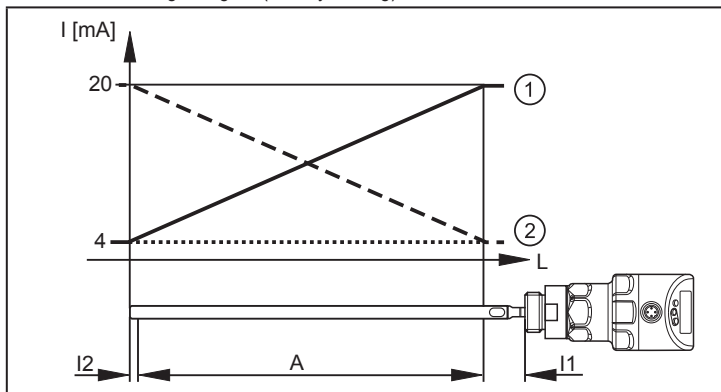
- [ou2] defines the output function of the analogue output:
 - current output rising ([ou2] = [I]) or
 - current output falling ([ou2] = [InEG]) (→ 11.4.6)
- The analogue start point [ASP2] defines at which measured value the analogue start value*) is provided (→ 11.4.7).
- The analogue end point [AEP2] defines at which measured value the analogue end value*) is provided (→ 11.4.7).

*) The analogue start value is 4 mA with [ou2] = [I] or 20 mA with [ou2] = [InEG].

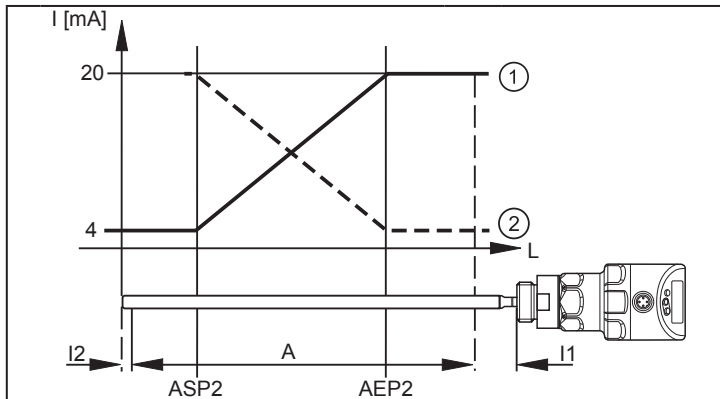
The analogue end value is 20 mA with [ou2] = [I] or 4 mA with [ou2] = [InEG].

Minimum distance between [ASP2] and [AEP2] = 20 % of the active zone.

Curve of the analogue signal (factory setting):



Curve of the analogue signal (measuring range scaled):



L: Level

A: Active zone = rod length $L - (I_1 + I_2)$

I_1 : Inactive zone 1

I_2 : Inactive zone 2 (→ Technical data sheet)

①: $[ou2] = I$ (factory setting)

②: $[ou2] = [InEG]$

ASP2: Analogue start point

AEP2: Analogue end point

Additional information about the analogue output: (→ 12.8)

Note the tolerances and accuracies during the evaluation of the analogue signal (→ Technical data sheet).

6.3.3 Switching functions

Via switching output OUT1 (factory setting) or additionally via OUT2 (can be set) the unit signals that a set limit level has been reached or that the level is below the limit. The following switching functions can be selected:

- Hysteresis function / normally open (fig. 6-3): $[oux] = [Hno]$
- Hysteresis function / normally closed (fig. 6-3): $[oux] = [Hnc]$

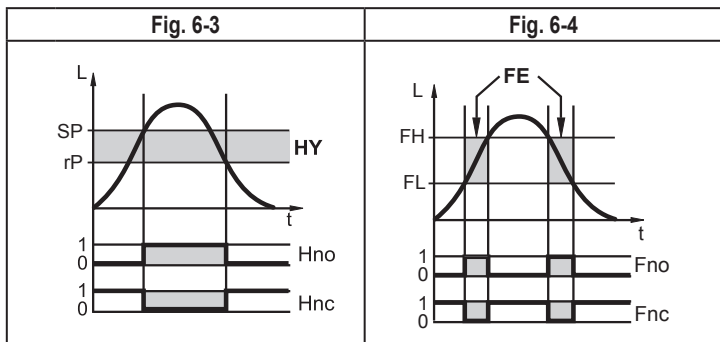


First the set point (SPx) is set, then the reset point (rPx) with the requested difference.

- Window function / normally open (fig. 6-4): $[oux] = [Fno]$
- Window function / normally closed (fig. 6-4): $[oux] = [Fnc]$



The width of the window can be set by means of the difference between FHx and FLx. FHx = upper value, FLx = lower value.



L: Level
 HY: Hysteresis
 FE: Window

- The adjustable limits (e.g. SP / rP) always refer to the lower edge of the rod.
- For the switching output a switch-on and switch-off delay of max. 60 s can be set (e.g. for especially long pump cycles) (→ 11.4.4).

6.3.4 Damping function

With unsteady level (e.g. turbulence, wave movements...) display and output response may be damped. During damping the determined level values are "smoothed" by means of a mean filter; the result is a steady curve. Damping can be set by means of the parameter [dAP] (→ 11.4.10).

[dAP] indicates in seconds after what time 63 % of the final value are reached in the event of a sudden jump. After 5 x [dAP] almost 100 % have been reached.

6.3.5 Rods for different tank heights

- The unit can be installed in tanks of different sizes. Rods in different lengths are available. To adapt to the tank height, each rod can be shortened. The minimum probe length is 150 mm, the maximum probe length is 2000 mm.
- For ease of installation and removal the rod connection can be rotated without restriction.

6.3.6 Defined state in case of a fault

- In case of a fault a state can be defined for each output.
- If a fault is detected or if the signal quality is below a minimum value, the outputs pass into a defined state, according to NAMUR recommendation in case of the analogue output. For this case the response of the outputs can be set via the parameters [FOU1], [FOU2] (→ 11.4.9).
- Temporary loss of signal caused e.g. by turbulence or foam formation can be suppressed by a delay time (parameter [dFo] (→ 11.4.11)). During the delay time the last measured value is frozen. If the measured signal is received again in sufficient strength within the delay time, the unit continues to work in normal operation. If, however, it is not received again in sufficient strength within the delay time, the outputs pass into the defined state.



In case of heavy foam formation and turbulence, note the examples of how to create a steady area (→ 7.2.6).

6.3.7 IO-Link

This unit has an IO-Link communication interface which requires an IO-Link capable module (IO-Link master) for operation.

The IO-Link interface enables direct access to the process and diagnostic data and provides the possibility to set the parameters of the unit during operation.

In addition, communication is possible via a point-to-point connection with a USB adapter cable.

The IODDs necessary for the unit's configuration, detailed information about process data structure, diagnostic information, parameter addresses and the necessary information about required IO-Link hardware and software can be found at www.ifm.com.

6.3.8 Simulation functions

Various levels and errors can be simulated for set-up, maintenance or interference reduction. The duration of the simulation can be selected (1 min...1 h). The simulation can be started manually and runs until it is stopped manually or the set time elapses. During the simulation the outputs respond according to the simulated process values (→ 11.7) to (→ 11.7.3).

7 Installation

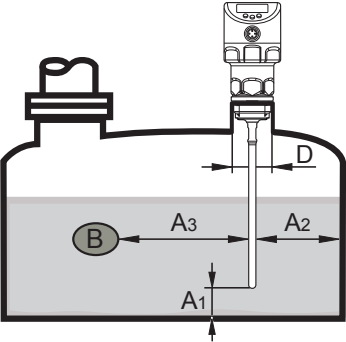
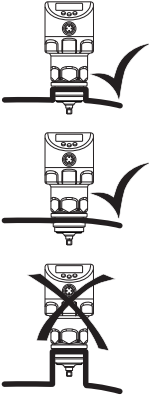
7.1 Installation location / environment

- Vertical installation from the top is preferred.

7.2 Unit with single probe

- ▶ Observe the notes on tank adjustment (→ 7.2.7).
- Installation preferably in closed, metal tanks or metal bypass pipes
- For installation in open tanks: (→ 7.6.3)
- For installation in plastic tanks: (→ 7.6.4)
- When operating the unit in small tanks (probe lengths shorter than 200 mm and less than 300 mm distance to the tank wall), mount the unit off-centre (eccentrically) to prevent possible interference from tank resonances.

7.2.1 Minimum distances and minimum connection piece diameter


Fig. 7-1	Fig. 7-2
	<p data-bbox="640 139 866 168">Without adjustment</p> 
Installation distances with adjustment (→ 7.2.7)	Installation distances without adjustment
A1: 10 mm	A1: 10 mm
A2: 20 mm	A2: 50 mm
A3: 20 mm to tank structures (B) 50 mm to other sensors type LR	A3: 50 mm to tank structures (B) 50 mm to other sensors type LR
D: \varnothing 30 mm if installed in a connection piece	D: No connection piece allowed according to fig. 7-2

7.2.2 Installation in pipes

- ▶ Only install the unit in metal pipes.
- ▶ The internal pipe diameter d must at least have the following value:

	With adjustment(→ 7.2.7)	Without adjustment
d	\varnothing 30 mm	\varnothing 100 mm with [MEdI] = [HIGH] \varnothing 250 mm with [MEdI] = [Mid] (→ 11.2.3)

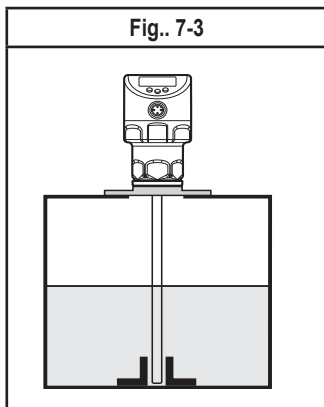
- ▶ If possible, mount the unit off-centre (eccentrically).

 Depending on the operating conditions (flow) and mechanical design of the pipe the use of centring pieces is recommended (→ Accessories).

7.2.3 Applications with viscous and fast flowing media

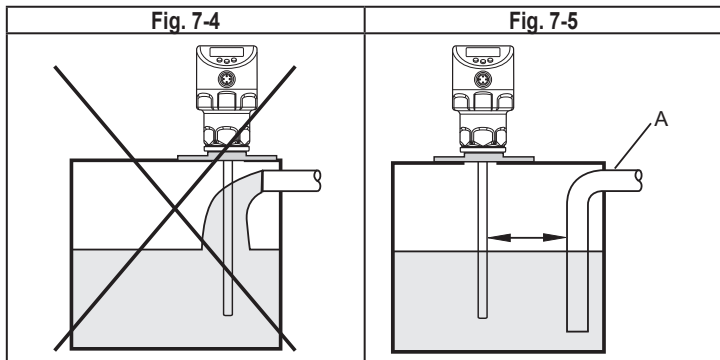
For applications with viscous or flowing media and / or agitators in which the rod is exposed to lateral load:

- ▶ Rod must not be in contact with tank wall / structures.
- ▶ Increase lateral minimum distances according to the rod length and the lateral deflection to be expected.
- ▶ If possible, fix the rod at the tank bottom so that it is electrically conductive. This can be done by means of a sleeve or similar devices (fig. 7-3).
- ▶ Check the correct function (in particular with empty tank).



7.2.4 Fill openings

Do not install the unit in the immediate vicinity of a fill opening (fig. 7-4). If possible, install a fill pipe (A) in the tank (fig. 7-5). Keep to the indicated installation distances, if needed carry out tank adjustment.



7.2.5 In case of heavy soiling

If the medium is highly polluted, there is the risk that a bridge forms between the rod and the tank wall or structures in the tank.

- Increase minimum distances depending on the pollution intensity.

7.2.6 Heavy foam build-up and turbulence



Heavy foam build-up and turbulence may lead to incorrect measurements.

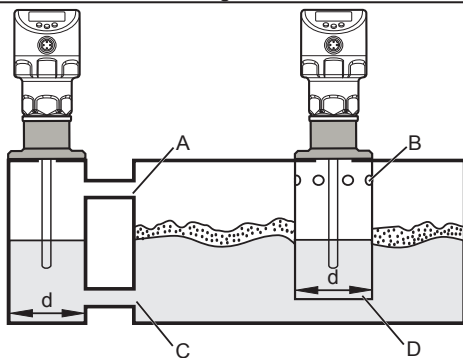
To avoid this

- Install the sensor in a steady area.

Examples how to create a steady area:

- Use of a coaxial probe (only for clean, low-viscosity media)
- Installation in metal bypass or metal still pipe (fig. 7-6)
- Separation of the installation location by metal sheets / perforated sheets (without figure)


Fig. 7-6





d: Minimum diameter (→ 7.2.2)



The upper access to the steady area (A, B) must be above the max. level. The lower access (C, D) or the area with perforated sheet must be below the min. level. This ensures that neither foam nor turbulence impact the sensor zone. When perforated sheets or similar are used, soiling (e.g. solids in the medium) can also be avoided.

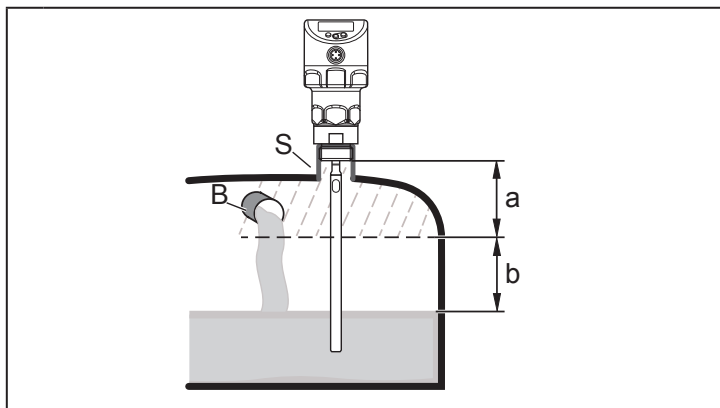
-  With increased foam formation the setting [MEdI] = [MId] is recommended (→ 11.2.3).

7.2.7 Notes on tank adjustment

-  Tank adjustment reduces the effect of interference and ensures a higher excess gain in difficult application conditions.
-  Carry out the tank adjustment only when the unit is installed.

For the tank adjustment it is necessary to enter an "adjustment distance" first. Within this distance, starting from the process connection, interfering reflections are compensated.

- ▶ Select an adjustment distance (a) so that the connection piece (S) and structures in the tank (B) are completely detected.
- ▶ Observe safety distance (b ≥ 250 mm) to the level or the rod end.




a: Adjustment distance (min: 10 mm; max: L - 250 mm)


b: Safety distance to the level or rod end: b ≥ 250 mm

S: Connection piece


B: Structures in the tank

-  For probe lengths L < 260 mm no tank adjustment is possible. The parameter [tREF] is then not available. In this case:

- ▶ Adhere to all indicated installation distances (→ 7.2).

 No tank adjustment is necessary if all installation distances (→ 7.2) are adhered to. The unit is then ready for operation without tank adjustment.

▶ In case of doubt carry out a tank adjustment (recommended!).

 Carry out a tank adjustment with empty tank, if possible, to cover any possible interfering sources. In this case:

▶ Select the max. adjustment distance ($L - 250$ mm).

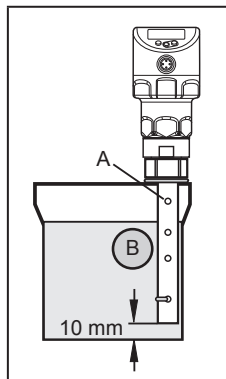
 Only if data storage is required in an IO-Link application:

The tank adjustment is not saved via IO-Link. After a replacement it must be carried out again.

More information about data storage: (→ 16.2)

7.3 Unit with coaxial probe

- No minimum distances to the tank wall and the baffles (B) are required.
- Minimum distance to the bottom of the tank: 10 mm.
- The vent hole (A) must not be covered by mounting elements or similar.
- Do not install the unit in the immediate vicinity of a fill opening. No water jets must enter into the holes of the coaxial pipe.



- Note in case of foam formation: The vent of the coaxial pipe must be above the maximum level. The lower edge of the coaxial pipe must be below the minimum level. This stops foam penetrating the coaxial pipe.

7.4 Installation of the rod

The probe is not supplied. It has to be ordered separately (→ 3 Items supplied).

7.4.1 Installation of the rod

Fixing of the rod:

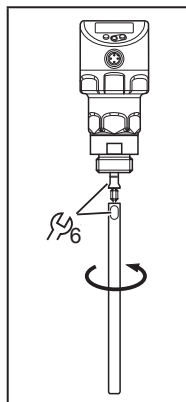
- ▶ Screw the rod to the unit and tighten it.



Recommended tightening torque: 4 Nm.

For ease of installation and removal the rod connection can be rotated without restriction. Even if rotated several times there is no risk of damage to the unit.

In case of high mechanical stress (strong vibration, moving viscous media) it may be necessary to secure the screw connection, e.g. by a screw retaining compound.



Substances such as screw retaining compounds may migrate into the medium.

- ▶ Make sure that they are harmless.

When using mechanical means of securing (e.g. tooth lock washer):

- ▶ Avoid protruding edges. They may cause interference reflection.

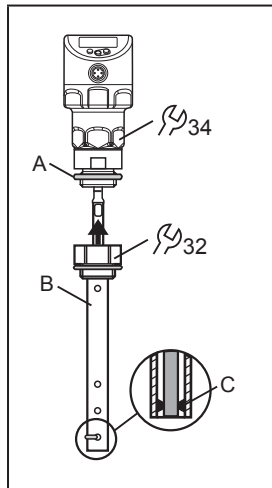
7.4.2 Installation of the coaxial pipe

This subchapter is only relevant if the unit is to be operated with a coaxial probe.



The coaxial pipe and the rod must be of the same end length. The coaxial pipe can be shortened (→ 7.5.2).


- ▶ Screw the rod to the unit and tighten it.
Recommended tightening torque: 4 Nm.
- ▶ Slide the supplied flat seal (A) onto the thread.
The elastomer seal may remain on the unit.
- ▶ Slide the coaxial pipe (B) onto the rod.
Carefully centre it and carefully move the rod through the centring piece (C) (for lengths > 1400 mm through both centring pieces) of the coaxial pipe. Do not damage the centring pieces.
- ▶ Screw onto the sensor thread and tighten.
Recommended tightening torque: 35 Nm




7.5 Rod length

7.5.1 Shortening of the rod

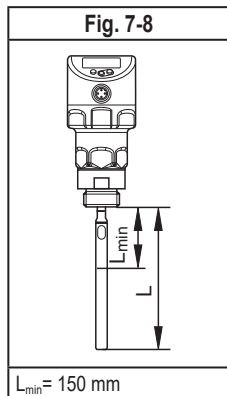
The rod can be shortened to adapt to different tank heights.

 Ensure that the rod length is not below the minimum permissible rod length of 150 mm (L_{\min}). The unit does not support rod lengths below 150 mm.


 For probe lengths < 260 mm no tank adjustment is possible (\rightarrow 7.2.7)

Proceed as follows:

- ▶ Screw the rod to the unit.
- ▶ Mark the desired length (L) on the rod. The reference point is the lower edge of the process connection (fig. 7-8).
- ▶ Remove the rod from the unit.
- ▶ Shorten the rod at the mark.
- ▶ Remove all burrs and sharp edges.
- ▶ Screw the rod to the unit again and tighten it. Recommended tightening torque: 4 Nm



In case of high mechanical stress (strong vibration, moving viscous media) it may be necessary to secure the screw connection, e.g. by a screw retaining compound.

 Substances such as screw retaining compounds may migrate into the medium.

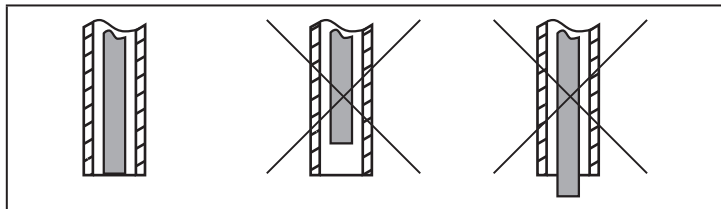
- ▶ Make sure that they are harmless.

7.5.2 Determine rod length L for single probes

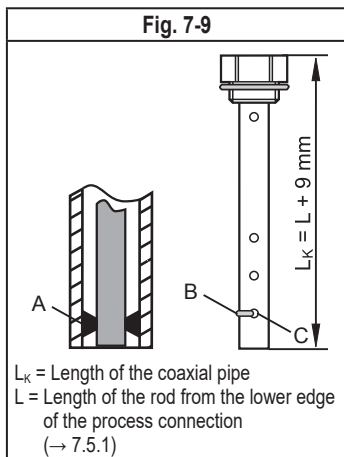
- ▶ Precisely measure the rod length L . The reference point is the lower edge of the process connection (fig. 7-8).
- ▶ Note the value. It is needed for setting the device parameters (\rightarrow 11.2).

7.5.3 Shortening of the coaxial pipe

The coaxial pipe and the rod must be of the same end length:



- ▶ Remove fastening bracket and centring piece (A, B).
- ▶ Shorten the coaxial pipe to the requested length: $L_K = L + 9$ mm
- ▶ After shortening, at least one hole (C) for insertion of the fixing bracket has to be left.
- ▶ Remove all burrs and sharp edges.
- ▶ Insert centring piece (A) at the lower end of the pipe (for lengths > 1400 mm use a second centring piece in the middle of the pipe) and attach it using the fixing bracket (B) at the lower hole (C).



7.5.4 Determine rod length L for coaxial probes

- ▶ Measure the exact total length L_K of the coaxial pipe (fig. 7-9, on the right).
- ▶ Deduct 9 mm from the total length of the coaxial pipe: $L_K - 9$ mm = L.
- ▶ Note down L. It is needed for setting the device parameters (→ 11.2).

7.6 Installation of the unit with single probe

- !** Before installing and removing the unit: Make sure that no pressure is applied to the system and that there is no medium in the tank that could leak. Also always take into account the potential dangers related to extreme machine and medium temperatures.

For installation in closed metal tanks, the tank lid serves as a launching plate R (fig. 7-10, fig. 7-12) and (→ 12.1).

Options are as follows:

- Installation to G^{3/4} process connection directly in the tank lid (→ 7.6.1)
- Installation in the tank lid using a flange plate (e.g. for tanks with thin walls) (→ 7.6.2)

- i** During installation of the process connection on the tank lid observe the subsequent orientation of the housing (display orientation, cable outlet). The sensor housing cannot be rotated with respect to the internal thread! Subsequent alignment of the sensor housing is therefore not possible.

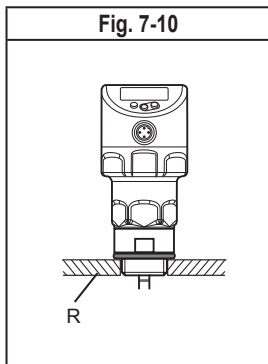
Furthermore, installation in open tanks (→ 7.6.3) and plastic tanks is possible (→ 7.6.4).

7.6.1 Installation to G^{3/4} process connection directly in the tank lid

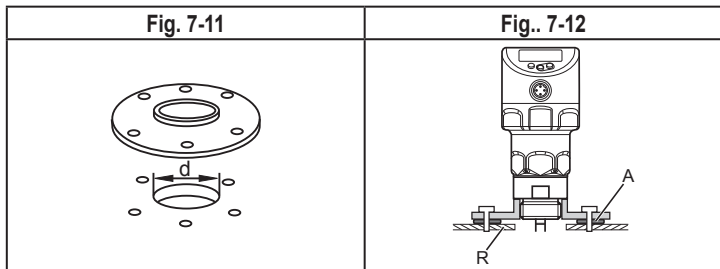
The elastomer seal on the sensor is used as process seal. The supplied flat seal can be used to smooth out unevenness on the tank lid process connection.

The upper sealing area on the process connection must be flush with the tapped hole.

- ▶ Slightly grease the sensor thread with a suitable paste.
- ▶ Insert the unit into the process connection.
- ▶ Tighten it using a spanner. Tightening torque: 35 Nm



7.6.2 Installation in the tank lid using a flange plate



- ▶ Arrange for a bore hole in the tank lid. It must have a minimum diameter d to enable sufficient transfer of the measured signal to the probe (fig. 7-11). The diameter (d) depends on the wall thickness of the tank lid:

Wall thickness [mm]	1...5	5...8	8...11
d [mm]	35	45	55

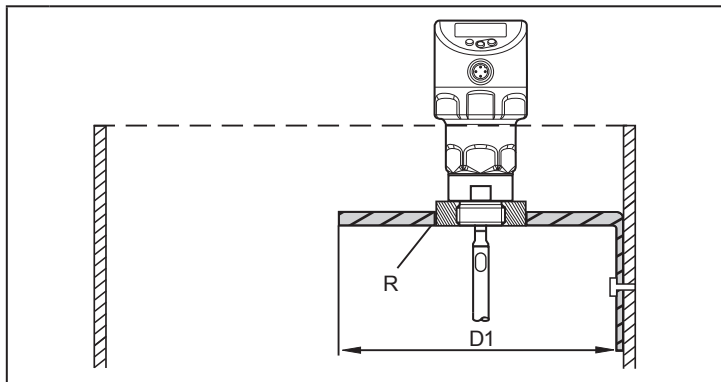
- ▶ Install the flange plate with the flat surface showing to the tank and fix it with appropriate screws.

! If necessary, a seal (A in fig. 7-12) can be inserted between flange plate and tank. Some flange plates are supplied with a seal. If this is not the case, use a suitable seal.

- ▶ Ensure cleanness and evenness of the sealing areas, especially if the tank is under pressure. Tighten the fixing screws sufficiently.
- ▶ Slightly grease the sensor thread with a suitable paste.
- ▶ Insert the unit into the process connection.
- ▶ Tighten it using a spanner. Tightening torque: 35 Nm

7.6.3 Installation in open tanks

- ▶ For installation in open tanks, use a metal fixture to install the unit. It serves as a launching plate R; minimum size: 150 x 150 mm for a square fixture, 150 mm diameter for a circular fixture (→ 12.1).
- ▶ If possible, mount the unit in the middle of the fixture. Adhere to the specified installation distances according to (→ 7.2), if necessary, carry out a tank adjustment.

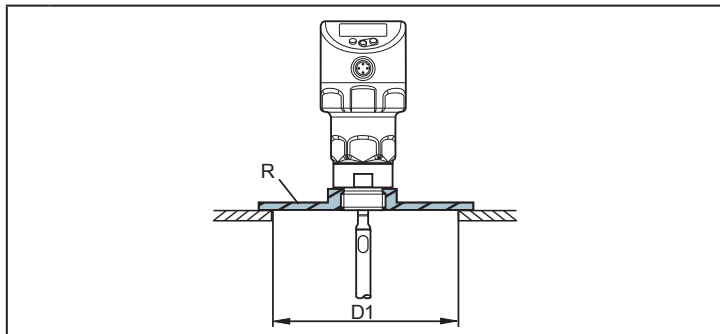


D1: Min. 150 mm.

R: Launching plate

- ▶ Slightly grease the sensor thread with a suitable paste.
- ▶ Insert the unit into the process connection.
- ▶ Tighten it using a spanner. Tightening torque: 35 Nm

7.6.4 Installation in plastic tanks



D1: Min. 150 mm

R: Launching plate

To enable sufficient transfer of the measured signal, note in case of installation in plastic tanks or metal tanks with plastic lid:

- ▶ A drill hole with a minimum diameter of 150 mm must be applied to the plastic lid.
- ▶ For installation of the unit, a metal flange plate (= launching plate, R) must be used which sufficiently covers the drill hole (→ 12.1).
- ▶ Ensure a minimum distance (= 80 mm) between the rod and the tank wall. Adhere to the installation instructions (→ 7.2.2) to (→ 7.2.6), if necessary carry out a tank adjustment.



When installed in plastic tanks, there may be deterioration caused by electromagnetic interference from other devices. Corrective measures:

- Apply a metal foil to the outside of the tank.
 - Apply a shielding screen between the level sensor and other electronic units.
 - Operation with coaxial probe efficiently protects the unit from electromagnetic interference. Observe application area (→ 5.2).
- ▶ Slightly grease the sensor thread with a suitable paste.
 - ▶ Insert the unit into the process connection.
 - ▶ Tighten it using a spanner. Tightening torque: 35 Nm

7.7 Installation of the unit with coaxial probe

- ▶ Seal the process connection:
 - For coaxial pipes with G $\frac{3}{4}$ process connection:
Slide the supplied seal onto the thread of the coaxial pipe.
 - For coaxial pipes with $\frac{3}{4}$ " NPT process connection: Apply a suitable sealing material (e.g. PTFE tape) to the thread of the coaxial pipe.
- ▶ Insert the unit with the coaxial pipe into the tank.
- ▶ Tighten it using a spanner. Tightening torque: 35 Nm

7.8 Alignment of the sensor housing



The sensor housing cannot be rotated with respect to the internal thread!
Subsequent alignment of the sensor housing is therefore not possible.

Therefore, the subsequent orientation of the housing (display orientation, cable outlet) must be observed during installation of the process connection on the tank lid.

8 Electrical connection



The unit must be connected by a qualified electrician.

The national and international regulations for the installation of electrical equipment must be adhered to.

Voltage supply according to SELV, PELV.



For marine applications (if approval available for the device), additional surge protection is required.

► Disconnect power.

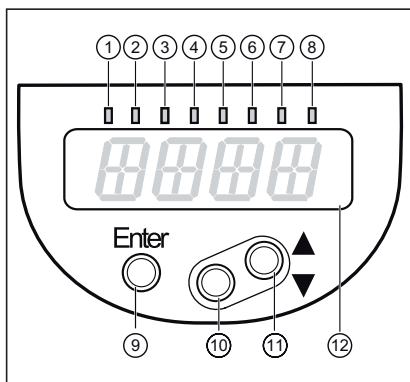
► Connect the unit as follows:

Core colours			
BK	Black		
BN	Brown		
BU	Blue		
WH	White		
		OUT1: Switching output / IO-Link	
		OUT2: Analogue output or switching output	
		Colours to DIN EN 60947-5-2	
Example circuits			
2 x positive switching		2 x negative switching	
1 x positive switching / 1 x analogue		1 x negative switching / 1 x analogue	



When operating voltage is applied to the unit for the first time, the basic settings must be entered first (→ 11.2). Only then is the unit ready for operation.

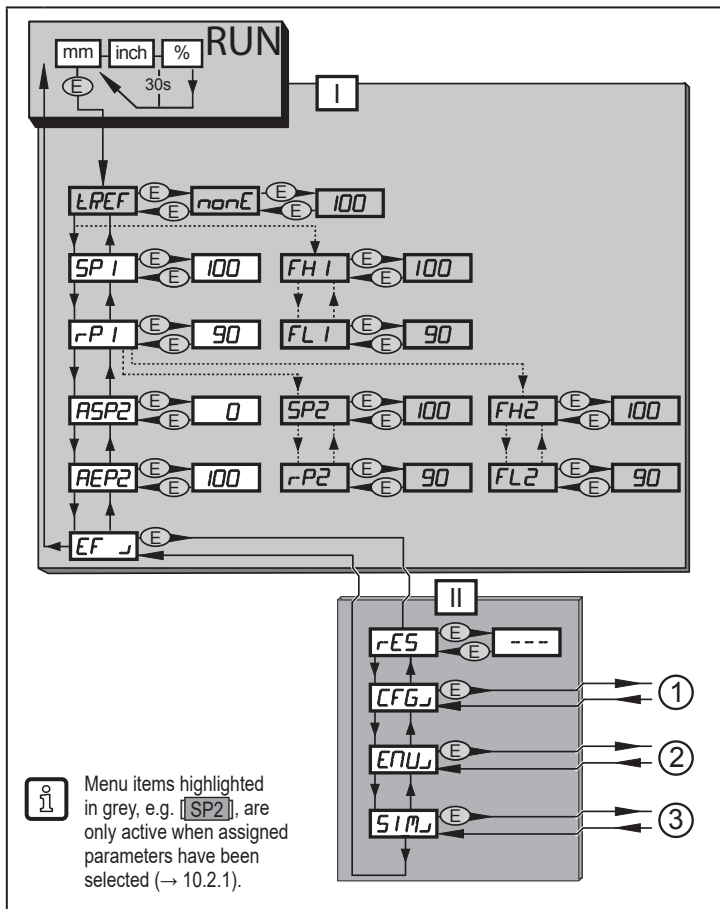
9 Operating and display elements



1 to 8: Indicator LEDs	
LEDs 1 - 3	Selected unit of measurement.
LEDs 4 - 6	Not used.
LED 7	Only active if the switching output [ou2] = [I] or [InEG] is selected; then: Switching status OUT2 (on when output 2 is switched).
LED 8	Switching status OUT1 (on when output 1 is switched).
9: [Enter] button	
<ul style="list-style-type: none"> - Open the user menu. - Edit and confirm the parameter values. 	
10 to 11: Arrow keys up [▲] and down [▼]	
<ul style="list-style-type: none"> - Selection of the parameters. - Setting of the parameter values (continuously by holding pressed; incrementally by pressing once). 	
12: Alphanumeric display, 4 digits	
<ul style="list-style-type: none"> - Display of the current level. - Indication of the parameters and parameter values. 	

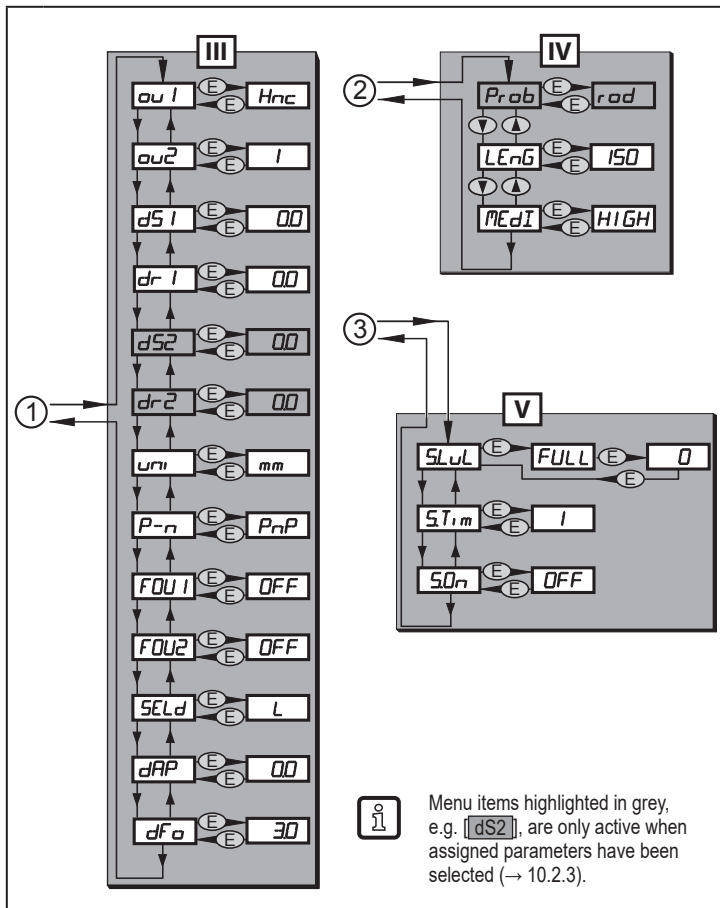
10 Menu

10.1 Menu structure



I: Main menu (→ 10.2.1)

II: EF Level (→ 10.2.2)



III : CFG level (→ 10.2.3)

IV : ENV level (→ 10.2.4)

V : SIM level (→ 10.2.5)

10.2 Explanation of the menu

10.2.1 Main menu [I]

tREF	Carry out tank adjustment. Menu item only visible if [LEnG] \geq 260 mm and [Prob] = [rod]
SP1 / rP1	Set point 1 / reset point at which OUT1 switches. Menu item only visible if hysteresis function is selected ([ou1] = [H..])
FH1 / FL1	Upper / lower limit for the acceptable range within which OUT1 switches. Menu item only visible if window function is selected ([ou1] = [F..])
ASP2	Analogue start point 2: Measured value at which the analogue start value is provided. The analogue start value is set with parameter [ou2]. Menu item only visible if analogue output is selected ([ou2] = [I] or [InEG])
AEP2	Analogue end point 2: Measured value at which the analogue end value is provided. The analogue end value is set with parameter [ou2]. Menu item only visible if analogue output is selected ([ou2] = [I] or [InEG])
SP2 / rP2	Set point 2 / reset point 2 at which OUT2 switches. Menu item only visible if hysteresis function is selected ([ou1] = [H..])
FH2 / FL2	Upper / lower limit for the acceptable range within which OUT2 switches. Menu item only visible if window function is selected ([ou1] = [F..])
EF ↵	Extended functions / opening of menu level 2

10.2.2 EF level (extended functions) [II]

rES	Restore factory setting
CFG↵	Open the submenu CFG (configuration)
ENV↵	Open the submenu ENV (environment parameter)
SIM↵	Open the submenu SIM (simulation)

10.2.3 CFG level (configuration) [III]

ou1	Output configuration for OUT1: <ul style="list-style-type: none">• Switching signal for level limit value. Hysteresis or window function, normally closed or normally open
ou2	Output configuration for OUT2: <ul style="list-style-type: none">• Analogue signal for current level, 4...20 mA or 20...4 mA or• Switching signal for level limit value. Hysteresis or window function, normally closed or normally open
dS1	Switch-on delay for OUT1
dr1	Switch-off delay for OUT1
dS2*)	Switch-on delay for OUT2
dr2*)	Switch-off delay for OUT2
uni	Selection of the unit of measurement on the sensor display (mm or inch)
P-n	Output polarity for the switching outputs (pnp or npn)
FOU1	Response of OUT1 in case of a fault
FOU2	Response of OUT2 in case of a fault
SEld	Selection of the type of indication
dAP	Damping of the measured signal (mean filter)
dFo	Delay time for the outputs to pass into the state defined with [FOUx]; only effective in case of a fault.
*) Menu item only visible with hysteresis or window function ([ou2] = [H..]) or [°F..]).	

10.2.4 ENV level (environment) [IV]

Prob*	Input of the type of probe (single probe or coaxial probe)
LEnG	Input of the rod length
MEdl	Medium selection
* Menu item only visible if [MEdl] = [HIGH] or [Mld].	

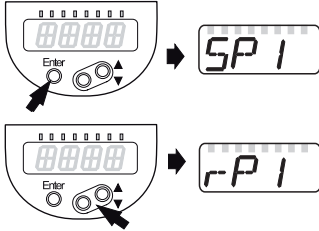
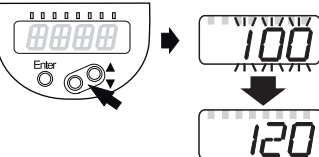
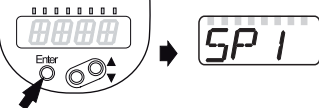
10.2.5 SIM level (simulation) [V]

S.LvL	Simulation of a level / an error state
S.Tim	Simulation duration 1...60 min
S.On	Simulation start/stop

11 Parameter setting

During parameter setting the device remains in the operating mode. It continues its monitoring functions with the existing parameters until the parameter setting has been completed.

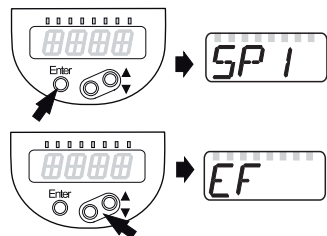
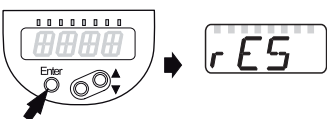
11.1 Parameter setting in general

<p>1 Select parameter</p> <ul style="list-style-type: none">▶ Press [Enter] to get to the menu.▶ Press [▲] or [▼] until the required parameter is displayed.	 <p>The diagram illustrates the selection of parameter SP1. It shows two states of the device's control panel. In the first state, the 'Enter' button is pressed, and the display shows 'SP1'. In the second state, the up/down arrow buttons are pressed, and the display shows 'rP1'.</p>
<p>2 Set parameter value</p> <ul style="list-style-type: none">▶ Press [Enter] to edit the selected parameter.▶ Press [▲] or [▼] for min. 1 s.> After 1 s: setting value is changed: Incrementally by pressing the button once or continuously by keeping the button pressed.	 <p>The diagram illustrates the setting of parameter value. It shows the device's control panel with the up/down arrow buttons being pressed. The display shows '100' and then '120'.</p>
<p>Numerical values are incremented continuously with [▲] or decremented with [▼].</p>	
<p>3 Acknowledge parameter value</p> <ul style="list-style-type: none">▶ Press [Enter].> The parameter is displayed again. The new setting value is saved.	 <p>The diagram illustrates the acknowledgment of parameter value. It shows the device's control panel with the 'Enter' button being pressed. The display shows 'SP1'.</p>
<p>Set other parameters</p> <ul style="list-style-type: none">▶ Press [▲] or [▼] until the required parameter is displayed.	
<p>Finish parameter setting</p> <ul style="list-style-type: none">▶ Press [▲] or [▼] several times until the current measured value is displayed or wait for 30 s.> The unit returns to the process value display.	



[C.Loc] or [S.Loc] as operation indication see (→ 12.7)

- Change from menu level 1 to menu level 2:

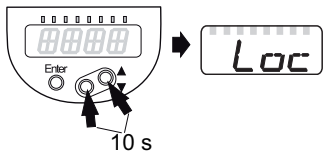
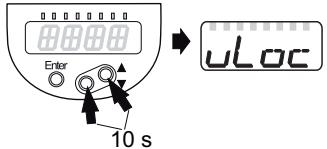
<ul style="list-style-type: none"> ▶ Press [Enter] to get to the menu. ▶ Press [▲] or [▼] until [EF] is displayed. 	 <p>The diagram shows two steps. In the first step, an arrow points to the 'Enter' button on a control panel with a display showing 'SP 1'. In the second step, an arrow points to the down arrow button on the same panel, with the display now showing 'EF'.</p>
<ul style="list-style-type: none"> ▶ Press [Enter]. > The first parameter of the submenu is displayed (here: [rES]). 	 <p>The diagram shows a control panel with a display showing 'rES'. An arrow points to the 'Enter' button.</p>

- Timeout:

If no button is pressed for 30 s during parameter setting, the unit returns to the process value display with unchanged values.

- Locking / unlocking

The unit can be locked electronically to prevent unintentional settings. Factory setting: not locked.

<ul style="list-style-type: none"> ▶ Make sure that the device is in the normal operating mode. ▶ Press [▲] + [▼] simultaneously for 10 s. > [Loc] is displayed. 	 <p>The diagram shows a control panel with a display showing 'Loc'. Two arrows point to the up and down arrow buttons, with a '10 s' label indicating the duration of the simultaneous press.</p>
<p>During operation: [Loc] is briefly displayed if you try to change parameter values.</p>	
<p>For unlocking:</p> <ul style="list-style-type: none"> ▶ Press [▲] + [▼] simultaneously for 10 s. > [uLoc] is displayed. 	 <p>The diagram shows a control panel with a display showing 'uLoc'. Two arrows point to the up and down arrow buttons, with a '10 s' label indicating the duration of the simultaneous press.</p>

11.2 Basic settings (set-up)

On delivery of the unit, you must first enter the basic settings. The complete user menu then opens.


11.2.1 Entering the type of probe used

<ul style="list-style-type: none">▶ Apply operating voltage.> The initial display <code>====</code> is shown.▶ Select [Prob] and set:▶ Press [Enter].> [nonE] is displayed.▶ Press [▲] or [▼] for min. 1 s and set the value: [rod] = Single probe, for the detection of: - water and water-based media. [COAX] = Coaxial probe, for the detection of: - oils and oil-based media. - water and water-based media.▶ Press [Enter].• The detection of water and water-based media is possible with the single probe as well as with the coaxial probe.• The detection of oils and oil-based media is only possible with the coaxial probe.	<i>Prob</i>
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11.2.2 Enter probe length

<ul style="list-style-type: none">▶ Select [LEnG].▶ Press [Enter].> [nonE] is displayed.▶ Press [▲] or [▼] for min. 1 s.> After 1 s the unit automatically displays the detected rod length (preset function*).▶ Correct the rod length, if necessary, with [▲] or [▼]. Incrementally by pressing the button once or continuously by keeping the button pressed. Enter the rod length in mm.▶ Press [Enter].	<i>LEnG</i>
<p>*) Automatic rod length detection is only possible with empty tank and sufficiently large launching plate.</p> <p>For manual determination of the rod length: (→ 7.5.2)</p>	

11.2.3 Setting to the medium

<p>▶ Select [MEdI] and set:</p> <p>[HIGH] = For water and water-based media. Operating mode is optimised for suppression of deposits on the rod.</p> <p>[MId] = For water-based media and media with a medium dielectric constant value, e.g. water-in-oil emulsions. Operating mode optimised for the detection of media with increased foam build-up.</p> <p>[LOW] = For oils and oil-based media Note: Option only visible if [Prob] = [COAx]</p> <p>▶ Press [Enter]. ▶ Check proper function by an application test.</p>	
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Then the unit changes to the operating mode.

If required (e.g. when mounted in a connection piece) carry out a tank adjustment (parameter [tREF]) and set parameters to adapt to the application.

Setting ranges of all parameters: (→ 13.1)

Factory settings of all parameters: (→ 15)

11.2.4 Carry out tank adjustment

<p>Menu item only visible if [LEnG] ≥ 260 mm and [Prob] = [rod].</p> <p>▶ Observe notes (→ 7.2.7).</p> <p>▶ Select [tREF].</p> <p>▶ Press [Enter].</p> <p>> [nonE] or the value stored by the last tank adjustment (distance value) is displayed.</p> <p>▶ Press [▲] or [▼] for min. 1 s.</p> <p>> The distance value is displayed (default value: 10 mm).</p> <p>▶ Correct the value, if necessary, with [▲] oder [▼]. Incrementally by pressing the button once or continuously by keeping the button pressed.</p> <p>▶ Press [Enter].</p> <p>> [donE] is displayed.</p> <p>▶ Press [Enter] again.</p> <p>> The unit reboots and then returns to the operating mode.</p>	
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11.3 Configure display (optional)

<ul style="list-style-type: none">▶ Select [uni] and set the unit of measurement: [mm], [inch]. Factory setting: mm.▶ Select [SELd] and set type of indication: [L] = The level is indicated in mm or inch. [%] = The level is indicated in percent of the measuring range / scaled measuring range. The level in percent depends on the parameters: [ASP2]: Set value corresponds to 0 % [AEP2]: Set value corresponds to 100 % [OFF] = The display is switched off in the operating mode. When one of the buttons is pressed, the current measured value is displayed for 30 s. The indicator LEDs remain active even if the display is deactivated.	
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11.4 Setting of output signals

11.4.1 Setting of the output function for OUT 1

<ul style="list-style-type: none">▶ Select [ou1] and set the switching function: [Hno] = Hysteresis function / normally open [Hnc] = Hysteresis function / normally closed [Fno] = Window function / normally open [Fnc] = Window function / normally closed <p>Note: If the switching output is used as an overflow prevention, the setting [ou1] = [Hnc] (normally closed function) is recommended. The principle of normally closed operation ensures that wire break or cable break is also detected.</p>	
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11.4.2 Set the switching limits (hysteresis function)

<ul style="list-style-type: none">▶ Make sure that the function [Hno] or [Hnc] is set for [oux]. Note: [I] is preset by the factory for [ou2], in this case [SP] / [rP] are not available.▶ Select [SPx] and set the value at which the output is set.	
<ul style="list-style-type: none">▶ Select [rPx] and set the value at which the output is reset. [rPx] is always smaller than [SPx]. The unit only accepts values which are lower than the value for [SPx].	

11.4.3 Set the switching limits (window function)

<ul style="list-style-type: none">▶ Make sure that for [oux] the function [Fno] or [Fnc] is set.▶ Select [FHx] and set the upper limit of the acceptable range.	<i>FH1</i> <i>FH2</i>
<ul style="list-style-type: none">▶ Select [FLx] and set the lower limit of the acceptable range. [FLx] is always lower than [FHx]. The unit only accepts values which are lower than the value for [FHx].	<i>FL1</i> <i>FL2</i>

11.4.4 Set switch-on delay for switching outputs

<ul style="list-style-type: none">▶ Select [dSx] and set the value between 0.0 and 60 s. The switch-on delay reacts according to VDMA*).	<i>dS1</i> <i>dS2</i>
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11.4.5 Set the switch-off delay for switching outputs

<ul style="list-style-type: none">▶ Select [drx] and set the value between 0.0 and 60 s. The switch-off delay reacts according to VDMA*).	<i>dr1</i> <i>dr2</i>
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*) According to VDMA the switch-on delay always has an effect on SP, the switch-off delay always on rP irrespective of whether the normally open or normally closed function is used.

11.4.6 Setting of the output function for OUT2

<ul style="list-style-type: none">▶ Select [ou2] and set the switching function: [I] = Current output 4...20 mA [InEG] = Current output 20...4 mA [Hno] = Hysteresis function / normally open [Hnc] = Hysteresis function / normally closed [Fno] = Window function / normally open [Fnc] = Window function / normally closed <p>Note: If the switching output is used as an overflow prevention, the setting [ou2] = [Hnc] (normally closed function) is recommended. The principle of normally closed operation ensures that wire break or cable break is also detected.</p>	<i>ou2</i>
--	------------

11.4.7 Scale analogue signal

<ul style="list-style-type: none">▶ Select [ASP2] and set the analogue start point.▶ Select [AEP2] and set the analogue end point. <p>These parameters can only be set via an IO-Link device tool if the parameter [ou2] is set to [I] or [InEG].</p> <p>More information: (→ 6.3.2)</p>	<i>ASP2</i> <i>AEP2</i>
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11.4.8 Set output logic for the switching outputs

- ▶ Select [P-n] and set [PnP] or [nPn].

P-n

11.4.9 Response of the outputs in case of a fault

- ▶ Select [FOU1] / [FOU2] and set the value:

[On] = Output switches ON in case of a fault

Analogue output switches to a value > 21 mA in case of a fault

[OFF] = Switching output switches OFF in case of a fault

Analogue output switches to a value < 3.6 mA in case of a fault.

Examples of faults: defective hardware, signal quality too low.

Overflow is not considered to be a fault!

FOU1
FOU2

11.4.10 Set damping for the measured signal

- ▶ Select [dAP] and set damping in seconds;
Setting range: 0.0...60.0 s
- ▶ More information: (→ 6.3.4).

dAP

11.4.11 Set delay time in case of a fault

- ▶ Select [dFo] and set a value between 0...10.0 s.

[dFo] only effective in case of a fault. Mind the dynamics of your application. In case of fast level changes it is recommended to adapt the value step by step.

More information: (→ 6.3.6)

dFo

11.5 Reset all parameters to factory setting

- ▶ Select [rES].
- ▶ Press [Enter] until [rES] is aligned right.
- ▶ Press and hold [▲] or [▼] until [---] is displayed.
- ▶ Press [Enter].
- > The unit reboots and the factory settings are restored.

Note: On delivery the unit is not operational. First, the first set-up must be made (→ 11.2).

rES

11.6 Changing basic settings


Required after changes to the rod or application.

11.6.1 Change the type of probe used

<p>Menu item only visible if [MEdI] = [HIGH] or [MId].</p> <ul style="list-style-type: none">▶ Select [Prob].▶ Press [Enter].▶ Press [▲] or [▼] for min. 1 s and set the value: [rod] = Single probe [COAX] = Coaxial probe▶ Press [Enter]. <p>More information: (→ 11.2.1)</p>	<i>Prob</i>
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11.6.2 Re-enter the rod length

<ul style="list-style-type: none">▶ Select [LEnG] and set probe length L. Note the set unit [uni].▶ Press [Enter]. <p>Note: After changing the rod length, the values for the switching limits must also be reviewed / re-entered.</p> <p>More information: (→ 11.2.2)</p>	<i>LEnG</i>
---	-------------

 After changing the rod length, a tank adjustment already made is deleted (→ 7.2.7)

11.6.3 Setting to another medium

<ul style="list-style-type: none">▶ Select [MEdI] and set: [HIGH] = For water and water-based media. [MId] = For water-based media and media with a mean dielectric constant value. [LOW] = For oils and oil-based media. <p>Note: Option only visible if [Prob] = [COAX].</p> <ul style="list-style-type: none">▶ Press [Enter]. <p>More information: (→ 11.2.3)</p>	<i>MEdI</i>
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11.7 Simulation

11.7.1 Set simulation value

<ul style="list-style-type: none">▶ Select [S.LvL]▶ Set the process value to be simulated: [Numerical value] = Level in mm / inch (depending on the basic setting) [FULL] = Full state [SEnS] = Weak measured signal [Err] = Electronic fault found [EPTY] = Empty state▶ Press [Enter].	<i>S.LvL</i>
--	--------------

11.7.2 Set simulation duration

<ul style="list-style-type: none">▶ Select [S.Tim].▶ Set time span for simulation. Setting range: 1, 2, 3, 4, 5, 10, 15, 20, 30, 45, 60 min. Factory setting: 3 min.	<i>S.Tim</i>
---	--------------

11.7.3 Switch simulation on / off

<ul style="list-style-type: none">▶ Select [S.On] and set: [OFF] = Simulation off [On] = Simulation on▶ Press [Enter] to start the simulation.	<i>S.On</i>
---	-------------



Simulation active until [Enter] is pressed again or the time set via [S.Tim] elapses. During the simulation [SIM] is displayed every 3 s. When the simulation has ended, [S.On] is displayed. The outputs react according to the simulated process values.



If the simulation is started via IO-Link, it can also only be finished via IO-Link. During the attempt to finish the simulation via the buttons, C.Loc is displayed.

12 Operation

12.1 Operation with single probe

The single probe is made up of one individual rod. Operation with a single rod is suited for the detection of aqueous media, in particular of heavily soiled aqueous media.



For correct function with single probe, the unit needs a sufficiently large metal launching surface / launching plate. It is necessary for transferring the microwave pulse to the tank with optimum transmission power.

For installation in closed metal tanks / metal bypass pipes, the tank lid / upper pipe section serves as a launching surface. For installation in open metal tanks, tanks made of plastic or metal tanks with plastic lids a sufficiently large fixing plate, a metal plate or similar must be used (→ 7.6.3) / (→ 7.6.4).

For operation with single probe, minimum distances to tank walls and structures in the tank must be adhered to (→ 7.2).

12.2 Operation with coaxial probe

The coaxial probe is made up of an inner rod and an outer probe pipe (coaxial pipe). The rod is centred in the coaxial pipe by one or several spacers.

In case of operation with a coaxial probe media with a low dielectric constant (e.g. oil and oil-based media) are detected in addition to aqueous media.



In addition, the following applies in case of operation with coaxial probe:

- No launching plate is required.
- No minimum distances to tank walls and objects in the tank need to be observed.
- No tank adjustment is necessary.



Observe application area (→ 5.2)

12.3 Function check

After power-on the device is in the operating mode. It carries out its measurement and evaluation functions and generates output signals according to the set parameters.

- ▶ Check whether the unit operates correctly.

12.4 Operation indication

---- continuous	Initialisation phase after power on
====	On delivery the unit is not operational. Basic settings required (→ 11.2).
[----]	Level below the active zone
Numerical value + LED 1	Current level in mm
Numerical value + LED 2	Current level in inches
Numerical value + LED 3	Current level in % of the scaled measuring range
LED 7	Switching status OUT2
LED 8	Switching status OUT1
[FULL] + numerical value alternately	Level has reached or exceeded the maximum measuring range (= overflow warning).
[Sim] + XXX alternately	Simulation active. XXX = state to be simulated (→ 11.7)
[S.On]	Simulation stopped(→ 11.7)
[Loc]	Unit locked via operating keys; parameter setting impossible. For unlocking press the two setting buttons for 10 s.
[uLoc]	Unit is unlocked / parameter setting is possible again
[C.Loc]	The unit is temporarily locked. Parameter setting via IO-Link active
[S.Loc]	Unit is permanently locked via software. This locking can only be removed via IO-Link.

12.5 Read the set parameters

- ▶ Briefly press [Enter] to open the menu.
- ▶ [▲] or [▼] scrolls through the parameters.
- ▶ Briefly press [Enter] to indicate the corresponding parameter value for about 30 s. Then the unit returns to the operating mode.

12.6 Change the display unit in the operating mode

(switching between length indication (mm / inch) and percentage).

► Briefly press [▲] or [▼] in the operating mode.

> The selected unit is displayed for 30 s, the corresponding LED is on. With each push of the button the display type is changed.

12.7 Error indications

	Possible cause	Recommended measures
[Err]	Fault in the electronics.	Replace the unit.
[nPrb]	Rod detached from the unit; possibly incorrect setting of the rod length.	Check whether the rod is still attached to the unit. Check the parameter [LEnG].
[SEnS]	Measurement disturbed by heavy foam build-up or turbulence.	<ul style="list-style-type: none">• Install the unit in a still pipe or bypass (→ 7.1).• Set / increment [dFo] (→ 11.4.11).
	Measurement disturbed by separation layers (e.g. oil layer on water).	<ul style="list-style-type: none">• Remove oil by suction• Stir the medium• Check composition
	Rod or process connection soiled.	Clean the rod and the process connection.
	Installation conditions were not adhered to.	<ul style="list-style-type: none">• Follow the installation instructions (→ 7)• Carry out or repeat a tank adjustment (→ 7.2.7).
	Probe length or sensitivity (setting to the medium) is incorrect.	Correct settings (→ 11.6), then carry out tank adjustment, if necessary (→ 11.2.4).
[SCx] + LED 7 [SCx] + LED 8	Flashing: short circuit in switching output OUT1 or OUT2.	Remove the short circuit.
[SC] + LED 7 + LED 8	Flashing: short circuit in both switching outputs	Remove the short circuit.
[PARA]	Faulty data set	Restore factory settings (→ 11.5).

12.8 Output response in different operating states

	OUT1	OUT2*
Initialisation	OFF	OFF
Normal operation	According to the level and [ou1] setting	According to the level 4...20 mA
Fault	OFF for [FOU1] = [OFF] ON for [FOU1] = [On]	< 3.6 mA at [FOU2] = [OFF] > 21 mA at [FOU2] = [On]
* If the analogue function [ou2] = [I] has been selected. If the switching function has been selected: see column OUT1		

Additional information about the analogue output:

Full signal: With [ou2] = [I]: 20...20.5 mA
With [ou2] = [InEG]: 4...3.8 mA

Empty signal: With [ou2] = [I]: 4...3.8 mA
With [ou2] = [InEG]: 20...20.5 mA

13 Technical data



Technical data and scale drawing at www.ifm.com

13.1 Setting ranges

[LEnG]	mm	inches
Setting range	150...2000	6.0...78.8
Step increment	5	0.2

The setting ranges for the switching limits [SPx], [rPx], [FHx], [FLx] depend on the rod length (L). In general the following applies:

	mm		inches	
	min	max	min	max
[SPx] / [FHx]	15 (35)	L - 30	0.6 (1.4)	L - 1.2
[rPx] / [FLx]	10 (30)	L - 35	0.4 (1.2)	L - 1.4
Step increment	1		0.05	
Note: The values in brackets apply to the setting [MEdl] = [LOW] (→ 11.2.3)				

- [rPx] / [FLx] is always smaller than [SPx] / [FHx]. If [SPx] / [FHx] is shifted, [rPx] / [FLx] also shifts provided that the lower end of the setting range is not reached. Always set [SPx] / [FHx] first, then [rPx] / [FLx].

The setting ranges for analogue start point [ASP2] and analogue end point [AEP2] depend on the rod length (L). In general the following applies:

	mm		inches	
	min	max	min	max
[ASP2]	0	---	0	---
[AEP2]	---	L - 30	---	L - 1.2
Step increment	1		0.05	

- Minimum distance between [ASP2] and [AEP2] = 20 % of the active zone.

14 Maintenance / Transport

- ▶ Keep the process connection free of deposits and foreign bodies.

In case of heavy soiling:


- ▶ Clean process connection and rod.


In case of longer operation separation layers can form in the medium (e.g. oil on water). This applies especially to still pipes or bypasses:

- ▶ Remove separation layers at regular intervals.

In case of operation with coaxial probe:

- ▶ Ensure that the vent hole (at the upper end of the coaxial pipe) remains free.
- ▶ Keep the interior of the coaxial pipe free from foreign bodies and soiling.

 When the medium is changed, it may also be necessary to adapt the unit settings (→ 11.2.3).

 Only if data storage is required in an IO-Link application:
The tank adjustment is not saved via IO-Link. After a replacement it must be carried out again (→ 11.2.4).

More information about data storage: (→ 16.2).

- ▶ It is not possible to repair the unit.
- ▶ After use dispose of the unit in an environmentally friendly way in accordance with the applicable national regulations.
- ▶ In case of returns ensure that the unit is free from soiling, especially of dangerous and toxic substances.
- ▶ For transport only use appropriate packaging to avoid damage of the unit.

15 Factory setting

	Factory setting	User setting
tREF	nonE	
SP1	50% VMR*	
rP1	5 mm below SP1	
ASP2	0% VMR*	
AEP2	100% VMR*	
dS1	0.0	
dr1	0.0	
ou1	Hno	
ou2	l	
uni	mm	
P-n	PnP	
FOU1	OFF	
FOU2	OFF	
SELd	L	
dAP	0.0	
dFo	3.0	
Prob	nonE	
LEnG	nonE	
MEdl	nonE	
S.LVL	50 % LEnG	
S.Tim	3	
S.On	OFF	

* VMR = final value of the measuring range = LEnG value minus 30 (in millimetres).
When the LEnG value is entered, the unit calculates the basic setting.

16 Notes on parameter setting via IO-Link



On delivery the unit is not operational.

During set-up, valid basic settings have to be sent to the device once even if the default settings correspond to the connected device. Make sure that the basic settings are entered correctly according to the attached rod and the medium to be detected.

16.1 Recommended procedure to avoid errors during parameter setting

- ▶ Enter rod length (parameter [LEnG]). Example: [LEnG] = [1000] mm.
- ▶ Scale analogue output (parameters [ASP2] and [AEP2]; [AEP2] must at least be 20 % greater than [ASP2!]). Example: [AEP2] = [970] mm.
 - ▶ Alternatively: Set parameter [ou2] to [H..] or [F..].
- ▶ Select the medium (parameter [MEdI]). Example: [MEdI] = [MId].
 - [HIGH] = For water and water-based media. Operating mode is optimised for suppression of deposits on the rod.
 - [MId] = For water-based media and media with a mean dielectric constant value. Operating mode is optimised for media with increased foam build-up.
 - [LOW] = For oils and oil-based media
- ▶ Transfer the sensor data to the unit.
- ▶ Carry out tank adjustment depending on the installation (parameter [tREF] or button "TEACH_TANK_REF").

If the adjustment distance (parameter [RefDist]) is to be adapted, this individual parameter has to be sent to the sensor first. Then the tank adjustment can be carried out. Select the adjustment distance according to, for example, the height of connection pieces or the position of structures in the tank. Within the adjustment distance, starting from the process connection, interfering reflections are compensated. Example: [RefDist] = [50] mm.

- ▶ Now all other settings can be carried out.



Only if data storage is required in an IO-Link application:

The tank adjustment is not saved via IO-Link. After a unit has failed it must be carried out again. Only when the tank adjustment has been carried out successfully does the unit revert to the cyclical process data transmission.



After a factory reset (button "Restore Factory Settings"), the device reboots and the factory settings are restored.

16.2 Unit locking / data storage

The IO-Link master stores all parameters of the connected sensor (except tank adjustment, see above) if configured in the master (data storage). When a sensor is replaced by a sensor of the same type, the parameters of the old sensor are automatically written to the new sensor if configured in the master and if the sensor allows this.

For safety reasons the parameter download can be refused by the sensor

Factory setting: [Open]

Data storage	- [Open] = Unit allows parameter download from the master
	- [Locked] = Unit refuses parameter download from the master

More information at www.ifm.com